



Modèle et méthode numérique d'ordres élevés pour la dynamique d'un spray polydisperse. Implémentation sur architectures hétérogènes à l'aide du runtime StarPU

Team HODINS – Cemracs16:
M. Essadki, A. Larat, J. Jung,
M. Pelletier, V. Perrier

■ ■ The CEMRACS 2016 Team: HODINS

Pau, Cagire Team



Vincent Perrier



Jonathan Jung

Paris, EM2C/IFPEn



Mohamed Essadki



Milan Pelletier

■ □ Outline

Context, Model and Numerics

Task-Driven Programming

Results

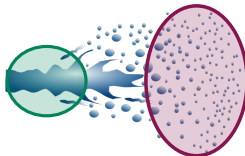
Context: atomization



Source: C. Dumouchel, CORIA Rouen.

Separated phases

- Smooth interface,
- Instabilities $\lambda \sim 1mm$.
- $Re_\lambda \sim 10^4$, $We_\lambda \gg 1$.



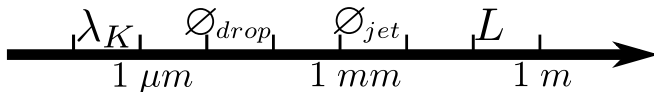
Source: J. Réveillon



Source: P. Edwards, Stanford

Disperse phase

- Polydisperse cloud ($d \sim 10\mu m$).
- Drag, collisions, evap., reaction...
- $Re_d < 100$, $We_d < We_c$



Very large range of scales ($\times 10^6$).

■ □ Eulerian moment method

Williams-Boltzmann ([4]) Equation: $f(t, \vec{x}, \vec{c}, S)$

$$\underbrace{\frac{\partial f}{\partial t} + \frac{\partial}{\partial \vec{x}} \cdot (\vec{c}f)}_{\text{Transport}} + \underbrace{\frac{\partial}{\partial \vec{c}} \cdot (\vec{F}f)}_{\text{Acceleration}} + \underbrace{\frac{\partial R_S f}{\partial S}}_{\text{Evap.}} = 0$$

Velocity Moments [3]

- $\mathcal{M}_m = \int \vec{c}^m f(t, \vec{x}, \vec{c}, S) d\vec{c}$

- Monokinetic: $\psi(\vec{c}, \vec{u}) = \delta(\vec{c} - \vec{u})$

$$\begin{cases} \partial_t n + \partial_{\vec{x}} \cdot (n\vec{u}) &= K \partial_S n, \\ \partial_t n\vec{u} + \partial_{\vec{x}} \cdot (n\vec{u} \otimes \vec{u}) &= n \frac{\vec{u}_g - \vec{u}}{\tau_p} + K \partial_S n\vec{u} \end{cases}$$

Fractional Size Moments [2]

- $m_{k/2} = \int_0^{S_{max}} S^{k/2} n(t, \vec{x}, S) dS$

$$\begin{cases} \Sigma_d \tilde{G}_d &= 4\pi m_{0/2}, \\ \Sigma_d \tilde{H}_d &= 2\sqrt{\pi} m_{1/2}, \\ \Sigma_d &= m_{2/2}, \\ \alpha_d &= \frac{1}{6\sqrt{\pi}} m_{3/2}. \end{cases}$$

■ □ Eulerian moment method

Simplifying Hypotheses:

$$f(t, \vec{x}, \vec{c}, S) = n(t, \vec{x}, S) \cdot \psi(\vec{c}, \vec{u}), \quad \vec{F} \text{ linear}, \quad R_S(S) = -K.$$

$$\frac{\partial f}{\partial t} + \frac{\partial}{\partial \vec{x}} \cdot (\vec{c} f) = \frac{\partial}{\partial \vec{c}} \cdot \left(\frac{\vec{c} - \vec{u}_g}{\tau_p} f \right) + K \partial_S f$$

Velocity Moments [3]

$$\blacksquare \mathcal{M}_m = \int \vec{c}^m f(t, \vec{x}, \vec{c}, S) d\vec{c}$$

$$\blacksquare \text{ Monokinetic: } \psi(\vec{c}, \vec{u}) = \delta(\vec{c} - \vec{u})$$

$$\begin{cases} \partial_t n + \partial_{\vec{x}} \cdot (n \vec{u}) &= K \partial_S n, \\ \partial_t n \vec{u} + \partial_{\vec{x}} \cdot (n \vec{u} \otimes \vec{u}) &= n \frac{\vec{u}_g - \vec{u}}{\tau_p} + K \partial_S n \vec{u} \end{cases}$$

Fractional Size Moments [2]

$$\blacksquare m_{k/2} = \int_0^{S_{max}} S^{k/2} n(t, \vec{x}, S) dS$$

$$\begin{cases} \Sigma_d \tilde{G}_d &= 4\pi m_{0/2}, \\ \Sigma_d \tilde{H}_d &= 2\sqrt{\pi} m_{1/2}, \\ \Sigma_d &= m_{2/2}, \\ \alpha_d &= \frac{1}{6\sqrt{\pi}} m_{3/2}. \end{cases}$$

■ □ Eulerian moment method

Simplifying Hypotheses:

$$f(t, \vec{x}, \vec{c}, S) = n(t, \vec{x}, S) \cdot \psi(\vec{c}, \vec{u}), \quad \vec{F} \text{ linear}, \quad R_S(S) = -K.$$

$$\frac{\partial f}{\partial t} + \frac{\partial}{\partial \vec{x}} \cdot (\vec{c} f) = \frac{\partial}{\partial \vec{c}} \cdot \left(\frac{\vec{c} - \vec{u}_g}{\tau_p} f \right) + K \partial_S f$$

Velocity Moments [3]

$$\blacksquare \mathcal{M}_m = \int \vec{c}^m f(t, \vec{x}, \vec{c}, S) d\vec{c}$$

$$\blacksquare \text{ Monokinetic: } \psi(\vec{c}, \vec{u}) = \delta(\vec{c} - \vec{u})$$

$$\begin{cases} \partial_t n + \partial_{\vec{x}} \cdot (n \vec{u}) &= K \partial_S n, \\ \partial_t n \vec{u} + \partial_{\vec{x}} \cdot (n \vec{u} \otimes \vec{u}) &= n \frac{\vec{u}_g - \vec{u}}{\tau_p} + K \partial_S n \vec{u} \end{cases}$$

Fractional Size Moments [2]

$$\blacksquare m_{k/2} = \int_0^{S_{max}} S^{k/2} n(t, \vec{x}, S) dS$$

$$\begin{cases} \Sigma_d \tilde{G}_d &= 4\pi m_{0/2}, \\ \Sigma_d \tilde{H}_d &= 2\sqrt{\pi} m_{1/2}, \\ \Sigma_d &= m_{2/2}, \\ \alpha_d &= \frac{1}{6\sqrt{\pi}} m_{3/2}. \end{cases}$$

System of equations, (Essadki [1, 2])

Fractional moment model: $f(t, \vec{x}, \vec{c}, S) = n(t, \vec{x}, S) \delta(\vec{c} - \vec{u})$, $\tau_p = \theta S$

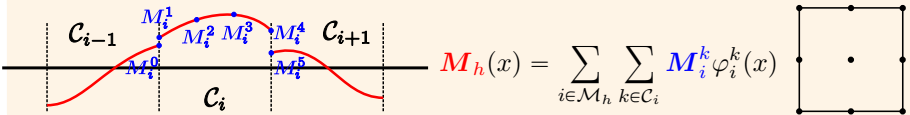
$$\left\{ \begin{array}{llll} \partial_t m_{0/2} & + & \partial_{\vec{x}} \cdot (m_{0/2} \vec{u}) & = & -K n(t, \vec{x}, S = 0), \\ \partial_t m_{1/2} & + & \partial_{\vec{x}} \cdot (m_{1/2} \vec{u}) & = & -\frac{K}{2} m_{-1/2}, \\ \partial_t m_{2/2} & + & \partial_{\vec{x}} \cdot (m_{2/2} \vec{u}) & = & -K m_{0/2}, \\ \partial_t m_{3/2} & + & \partial_{\vec{x}} \cdot (m_{3/2} \vec{u}) & = & -\frac{3K}{2} m_{1/2}, \\ \partial_t (m_{2/2} \vec{u}) & + & \partial_{\vec{x}} \cdot (m_{2/2} \vec{u} \otimes \vec{u}) & = & -K m_{0/2} \vec{u} + m_{0/2} \frac{\vec{u}_g - \vec{u}}{\theta}, \end{array} \right.$$

Operator splitting

$$\begin{aligned} \partial_t \mathbf{M} + \partial_{\vec{x}} \cdot \mathcal{F}(\mathbf{M}) &= 0, \\ \mathbf{d}_t \mathbf{M} &= -\mathcal{K} [n(t, \vec{x}, S)], \\ \mathbf{d}_t (m_{2/2} \vec{u}) &= m_{0/2} \frac{\vec{u}_g - \vec{u}}{\theta}. \end{aligned}$$

Advection: Numerical Discretization

Polynomial Discretization

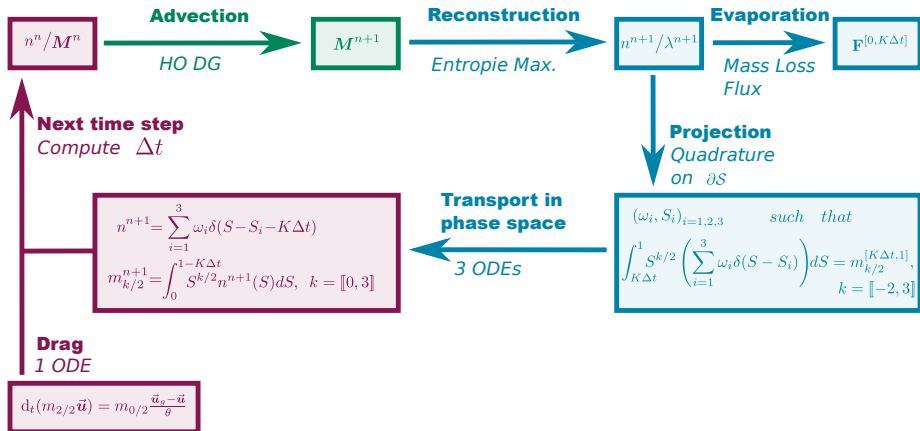


Discontinuous Galerkin Formulation

$$\partial_t \mathbf{M} + \partial_x \mathcal{F}(\mathbf{M}) = 0 \quad \Rightarrow \quad \int_{C_i} \left[\partial_t \mathbf{M}_h + \partial_x \mathcal{F}(\mathbf{M}_h) = 0 \right] \times \varphi_i^l$$

$$\underbrace{|\mathcal{C}_i| \sum_{k \in \mathcal{C}_i} \left(\int_{C_i} \varphi_i^l \varphi_i^k \right) \partial_t \mathbf{M}_i^k}_{\text{Time Evolution}} + \underbrace{\int_{\partial \mathcal{C}_i} \mathcal{F}^*(\mathbf{M}_i^{ext}, \mathbf{M}_i^{int}, \vec{\mathbf{n}})}_{\text{Numerical Flux (Surface)}} = \underbrace{\int_{C_i} \mathcal{F}(\mathbf{M}_h) \cdot \vec{\nabla} \varphi_i^l d\mathbf{x}}_{\text{Volumic Term}}$$

Global numerical procedure



■ ■ Outline

Context, Model and Numerics

Task-Driven Programming

Results

Heterogeneous Architectures (Top500)

Rank	Site	System	Cores	Rmax (TFlop/s)	Rpeak (TFlop/s)	Power (kW)
1	National Supercomputing Center in Wuxi China	Sunway TaihuLight - Sunway MPP, Sunway SW26010 260C 1.45GHz, Sunway NRPC	10,649,600	93,014.6	125,435.9	15,371
2	National Super Computer Center in Guangzhou China	Tianhe-2 (MilkyWay-2) - TH-IVB-FEP Cluster, Intel Xeon E5-2692 12C 2.200GHz, TH Express-Intel Xeon Phi 31S1P NUDT	3,120,000	33,862.7	54,902.4	17,808
3	DOE/SC/Oak Ridge National Laboratory United States	Titan - Cray XK7, Opteron 6274 16C 2.200GHz, Cray Gemini interconnect, NVIDIA K20x Cray Inc.	560,640	17,590.0	27,112.5	8,209
4	DOE/NNSA/LLNL United States	Sequoia - BlueGene/Q, Power BQC 16C 1.60 GHz, Custom IBM	1,572,864	17,173.2	20,132.7	7,890
5	RIKEN Advanced Institute for Computational Science (AICS) Japan	K computer, SPARC64 VIIIfx 2.0GHz, Tofu interconnect Fujitsu	705,024	10,510.0	11,280.4	12,660

Heterogeneous Architectures

Graphic Cards (GPU)

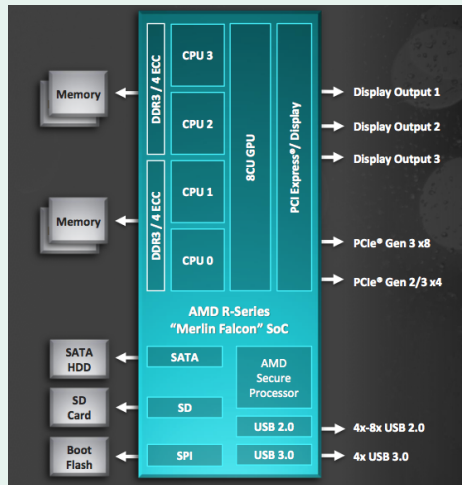
Jaguar Specs (2011)

Compute Nodes	18,668
Login & I/O Nodes	256
Memory per node	16 GB
# of Opteron cores	224,256
# of NVIDIA K20 "Kepler" accelerators (2013)	N/A
Total System Memory	300 TB
Total System Peak Performance	2.3 Petaflops

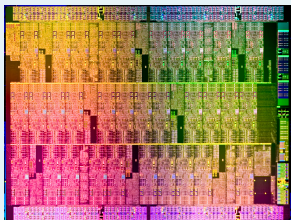
Titan Specs (2012)

Compute Nodes	18,668
Login & I/O Nodes	512
Memory per node	32 GB + 6 GB
# of Opteron cores	299,008
# of NVIDIA K20 "Kepler" accelerators (2013)	18,668
Total System Memory	710 TB
Total System Peak Performance	20+ Petaflops

System on Chips (SoC)



Many Integrated Core (MIC)



Task-driven Programming: a StarPU Lexicon

$$\textit{Task} = \underbrace{\textit{Codelet}}_{\text{Task Descriptor}} + \underbrace{\textit{Kernels}}_{\text{Executed Code}} + \underbrace{\textit{Data_handles}}_{\text{Memory Management}}$$

Example: $\vec{c} = \vec{a} + \vec{b}$.

Task

Codelet

- # of Handles = 3; $//(\vec{a}, \vec{b}, \vec{c})$
- Access Modes = $\{R, R, W\}$;
- CPU_Kernel = CPU;
- GPU_Kernel = GPU;

Data_handles

$\vec{a}$
handler

$\vec{b}$
handler

$\vec{c}$
handler

Kernels

CPU_Kernel

GPU_Kernel

$\vec{a}$

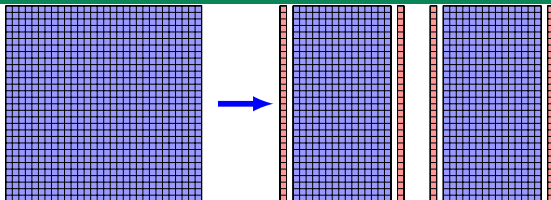
$\vec{b}$

$\vec{c}$

CPU.exe

GPU.exe

■ □ Description of the Tasks



Time Stepping

- InitialCondition
- StoreU0
- CheckTimeStep
- RKUpdate

Other

- FillOverlaps
- Drag
- Evaporation
- Positivity

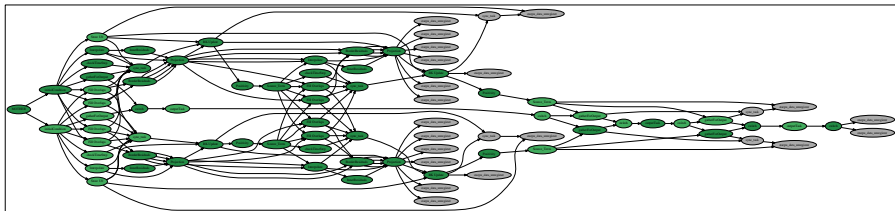
Advection Update

- Interpolate
- InnerResiduals
- Projection
- BorderResiduals

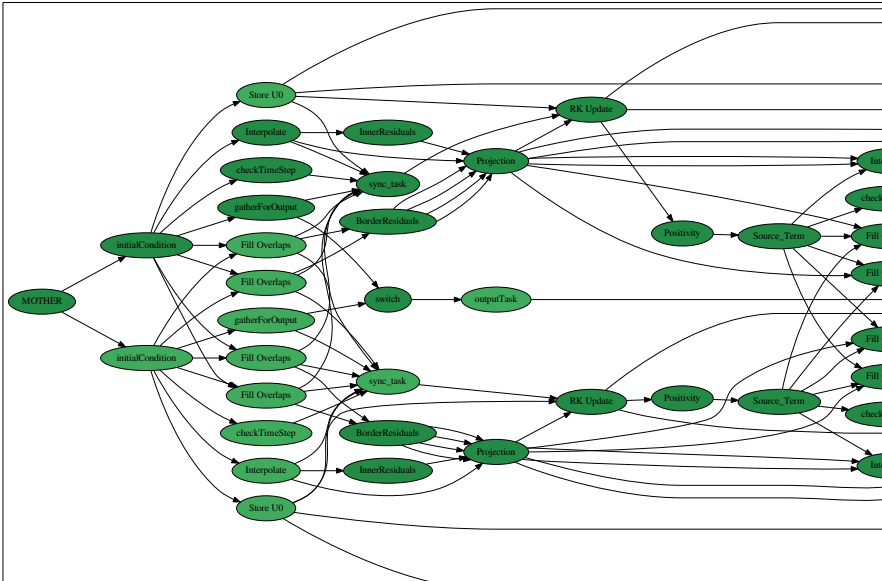
Input/Output

- gatherForOutput
- OutputTask

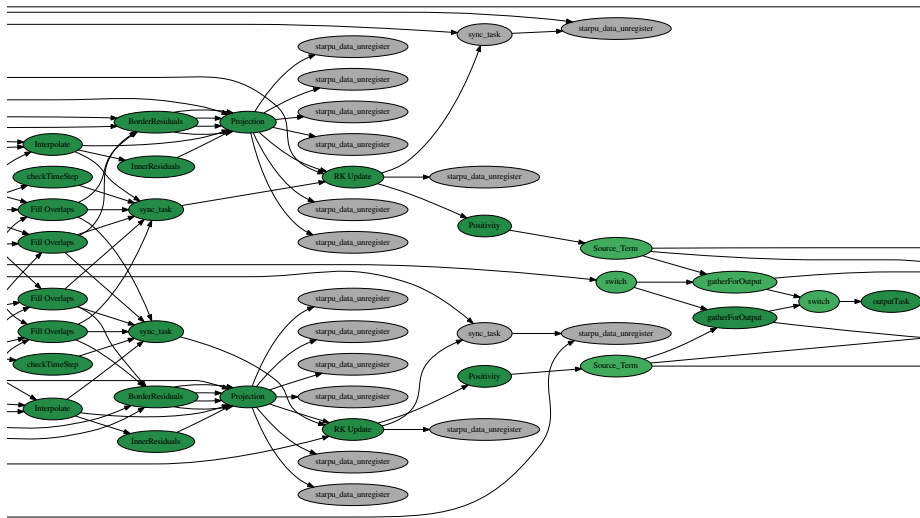
■ □ DG- $\mathbb{P}^1$ task diagram



■ ■ DG- $\mathbb{P}^1$ task diagram



DG- $\mathbb{P}^1$ task diagram



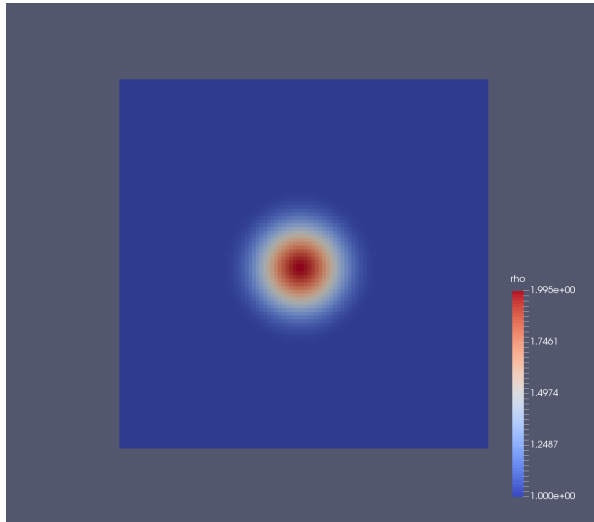
■ □ Outline

Context, Model and Numerics

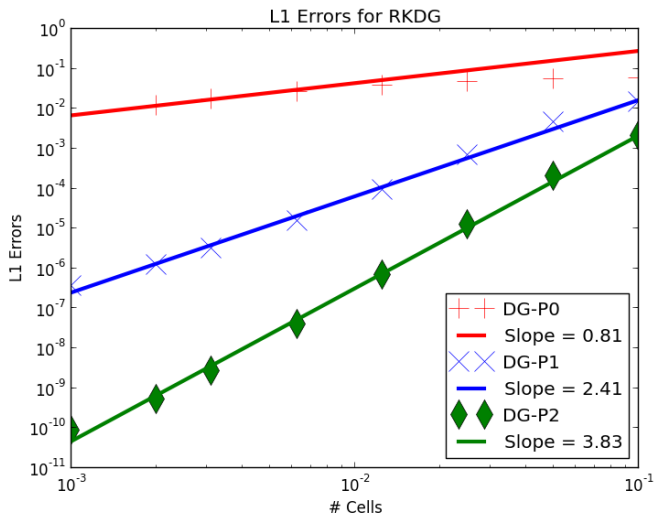
Task-Driven Programming

Results

Simple Advection

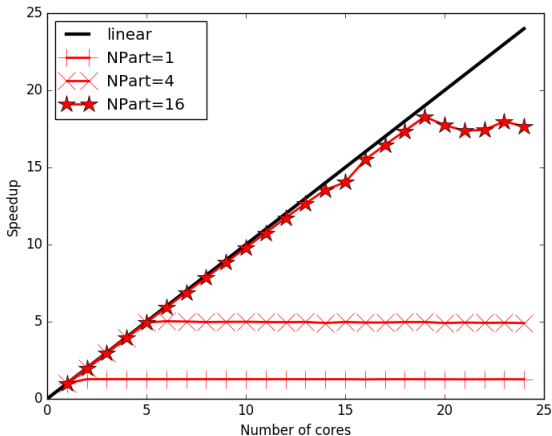


Numerical Convergence



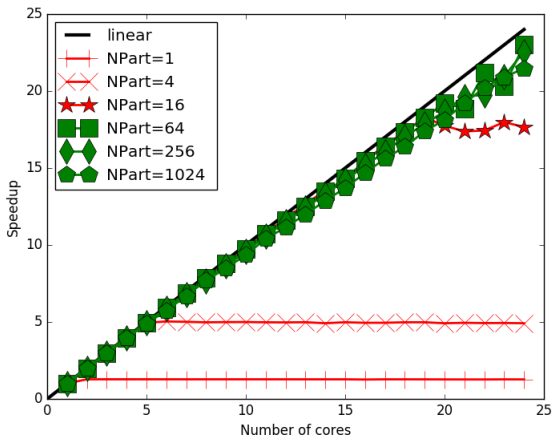
Parallel efficiency

Number of Tasks Limited Cases



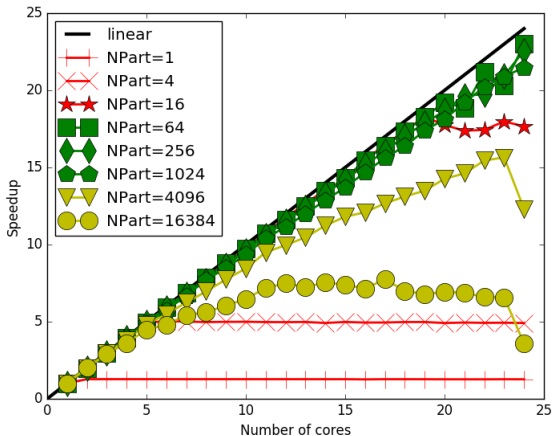
Parallel efficiency

Correct Scalling



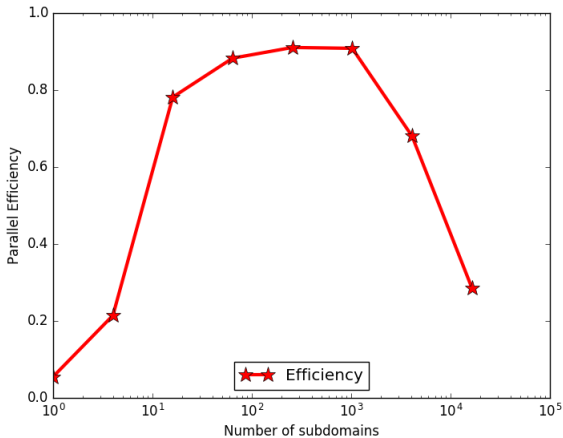
Parallel efficiency

Task Over-head Limitation



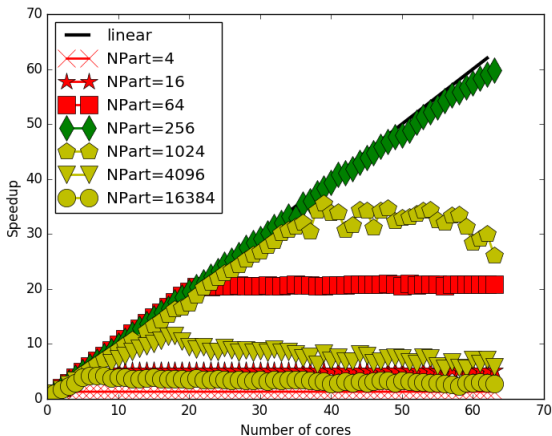
Parallel efficiency

Efficiency



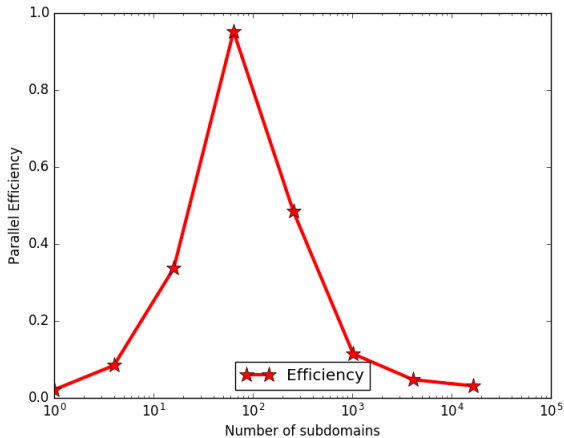
Parallel efficiency

Knights Landing Xeon Phi, 64 procs

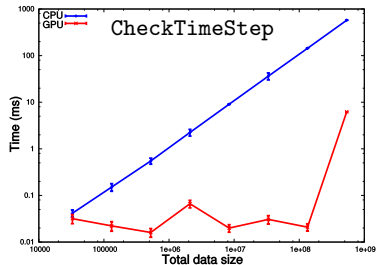
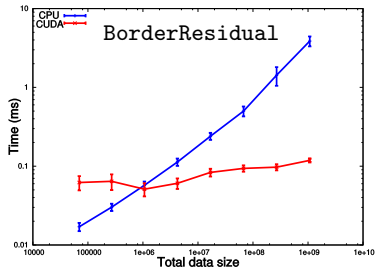
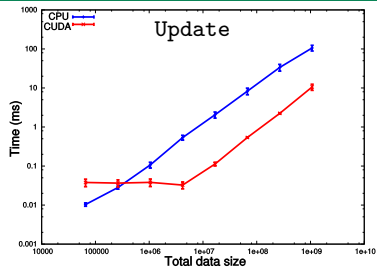
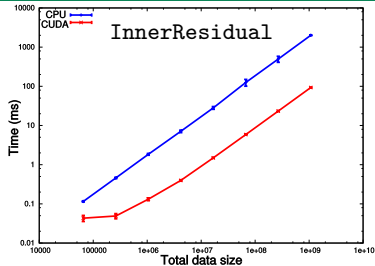


Parallel efficiency

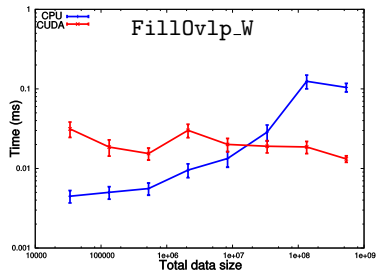
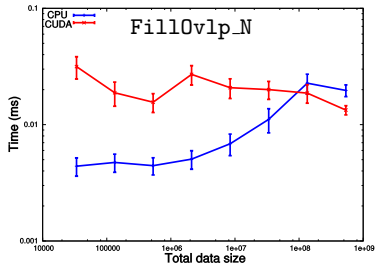
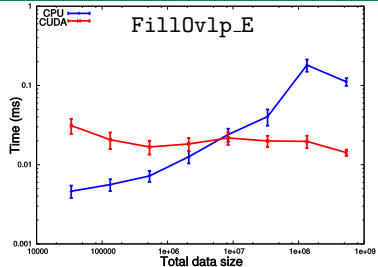
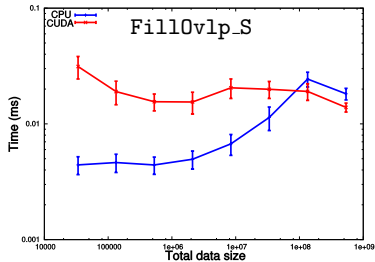
Efficiency



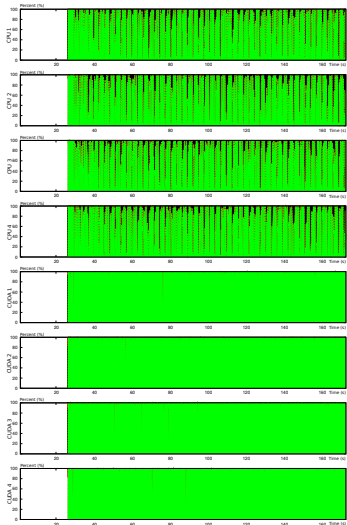
GPU: Some tasks are faster...



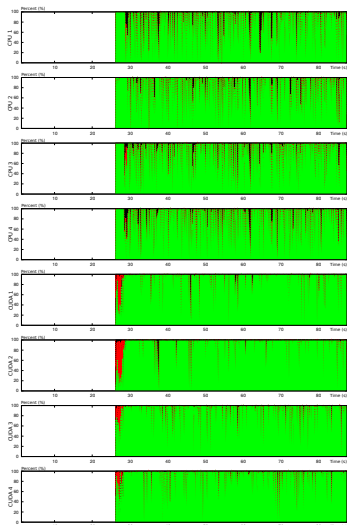
GPU: Some tasks are not!



Scheduler Choice

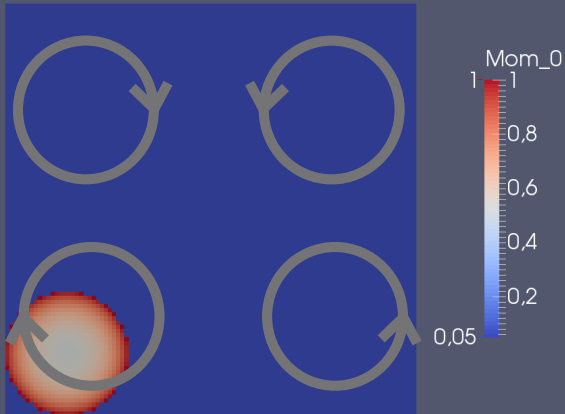


eager scheduler. Final time = 146s

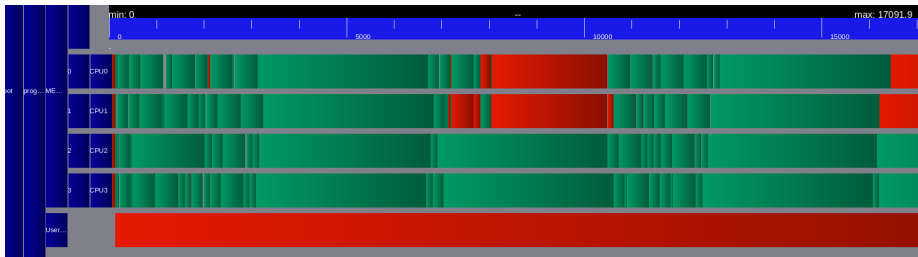


dmda scheduler. Final time = 61s

Evaporating spray: Taylor-Green vortex

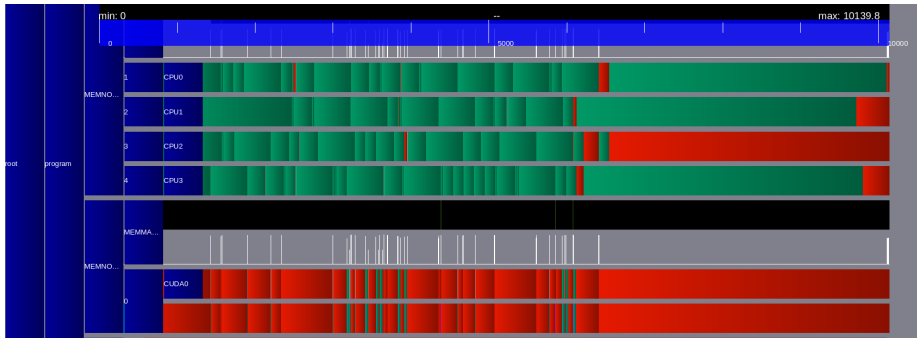


GPU Gain (6 domains, 4 CPUs, 2 GPUs)



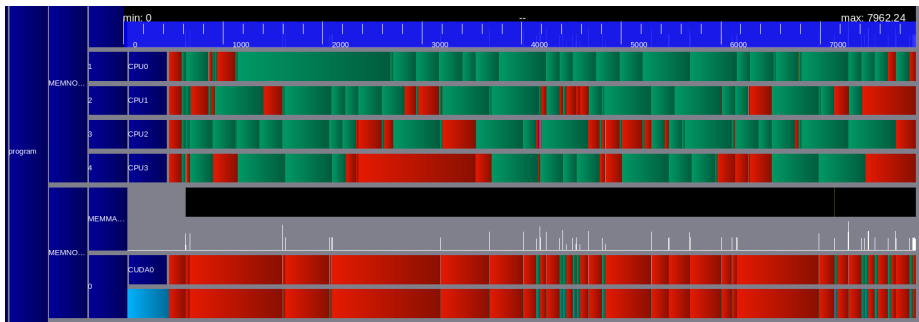
Gant Diagram on CPUs only. Final time = 17.09s.

GPU Gain (6 domains, 4 CPUs, 2 GPUs)



Some tasks are given to the GPUs. Final time = 10.13s.

GPU Gain (6 domains, 4 CPUs, 2 GPUs)



Better choice of scheduler. Final time = 7.96s.

■ □ Future Work

- MPI Extension
- Arbitrary High Order DG
- Look at other frameworks (Kokkos, DAGuE, ORCCA, ...)
- Integration within Aerosol

■ □ Acknowledgment

- IFPEn
- EDMH
- Groupe Calcul
- Plafrim
- Université Aix-Marseille
- CEMRACS 2016 organizing committee

References

- [1] M. Essadki, S. de Chaisemartin, M. Massot, F. Laurent, A. Larat, and S. Jay.
Adaptive mesh refinement and high order geometrical moment method for the simulation of polydisperse evaporating sprays.
Oil & Gas Science and Technology, pages 1–24, 2016.
- [2] M. Essadki, S. de Chaisemartin, F. Laurent, and M. Massot.
High order moment model for polydisperse evaporating sprays towards interfacial geometry description.
SIAM Applied Mathematics, pages 1–42, 2016.
submitted, <https://hal.archives-ouvertes.fr/hal-01355608>.
- [3] M. Massot, S. de Chaisemartin, L. Fréret, D. Kah, and F. Laurent.
Eulerian multi-fluid models : modeling and numerical methods.
In “*Modeling and computations of nanoparticles in fluid flows*”, pages 1–86. Lecture Notes of the von Karman Institute, RTO-EN-AVT 169, 2009.
Available on HAL : <http://hal.archives-ouvertes.fr/hal-00423031/en/>.
- [4] F.A. Williams.
Spray combustion and atomization.
Physics of Fluids, 1:541–545, 1958.